



# *Our Future:* **Built Better Together**

## Zero To Hero: Rookie to Pro-grammer

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# Agenda

- Where to start?
- Choosing a programming language
- Choosing a programming framework
- Accessing programming resources
- Going above and beyond
- Last but not least: Documentation



### Where to start



## Recruitment

External

• Advertisement in programming classrooms or coding clubs

Internal

- Programming based activities help teach programming concepts
  - Human Programming: Groups of students write pseudo-code to help a teammate complete an obstacle course.
  - Paper Planes



# Learning to Code

New to Programming

- Codecademy
- W3Schools

New to FRC Programming

• Nearby FRC teams



# Languages & Code Structure



# Choosing a language

- Java
  - Widely used in FRC
  - AP Comp Sci A
  - Recommended for new/inexperienced users
- C++
  - Also widely used
  - Not as common in Indiana as Java
  - Offers better high-end performance
- Python
  - Extremely Versatile
- LabView
  - Native to NI hardware (roboRIO)







# Choosing a framework



- Iterative Robot
  - The iterative robot base class handles the state transitions(Autonomous, Teleop, Disabled, Test)
- Command Based Robot
  - Design pattern that allows reuse year-to-year
  - New: Commands and Subsystems are interfaces granted extra flexibility
- TimedBot
  - Uses a timer to execute commands





# Accessing and Utilizing Resources



### Resources

WPILib:

https://docs.wpilib.org/en/stable/index.html

- Standard Software library provided for teams to write code for their FRC robots.
- Documentation for Java and C++
- Also offers guides for FRC LabVIEW Programming

RobotPy:

https://robotpy.readthedocs.io/en/stable/

Created by a community of FIRST mentors and students

LabView Robotics Guide: <a href="https://www.ni.com/pdf/manuals/372668d.pdf">https://www.ni.com/pdf/manuals/372668d.pdf</a>

Additional: https://frc-pdr.readthedocs.io/en/latest/vision/introduction.html



# **Above and Beyond**



# **Advanced Topics**

Sensors

 Allows for the tracking and measurement of different robot subsystems

PID Control

 Proportional, Integral, Derivative Loops that correct for error caused by sensors

Vision

Cameras + Vision Tracking

Packages

Organize classes and interfaces for easier year to year use



## Documentation



## **Git and GitHub**



- Git is the most widely used Version Control System
  - Code Collaboration and Version Control
- GitHub is a service that hosts remote repositories for Git version control



### Javadoc

\*Specific to the Java programming language\*

- Javadoc allows you to provide documentation while you program
  - Easier to have up to date documentation
  - Not an alternative to a manual or tutorial
  - Generates HTML files of API documentation

